# Average Case $L_{\infty}$ -Approximation in the Presence of Gaussian Noise

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We consider the average case  $L_{\infty}$ -approximation of functions from  $C^r([0, 1])$  with respect to the *r*-fold Wiener measure. An approximation is based on *n* function evaluations in the presence of Gaussian noise with variance  $\sigma^2 > 0$ . We show that the *n*th minimal average error is of order  $n^{-(2r+1)/(4r+4)} \ln^{1/2} n$ , and that it can be attained either by the piecewise polynomial approximation using repetitive observations, or by the smoothing spline approximation using non-repetitive observations. This completes the already known results for  $L_q$ -approximation with  $q < \infty$  and  $\sigma \ge 0$ , and for  $L_{\infty}$ -approximation with  $\sigma = 0$ . © 1998 Academic Press

## 1. INTRODUCTION AND MAIN RESULT

Optimal approximation of a function based on exact or noisy observations is one of the leading problems in approximation theory, statistics, and information-based complexity. Many different settings have been proposed to solve this problem. The settings are basically determined by whether we have deterministic or stochastic assumptions on the function and noise.

In this paper, we consider the average case setting, where both the function and the noise are assumed to be random. The problem is to approximate a real function f which belongs to the space

$$F^{r} = \{ f \in C^{r}([0, 1]): f^{(j)}(0) = 0, 0 \leq j \leq r \}$$

and is a realization of the stochastic process corresponding to the *r*-fold Wiener measure  $w^r$  on  $F^r$ ,  $r \ge 0$ . That is, the mean element of  $w^r$  is zero and the covariance kernel

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$$R_{r}(s, t) = \int_{F^{r}} f(s) f(t) w^{r}(df)$$
  
=  $\int_{0}^{1} \frac{(s-u)^{r}}{r!} \frac{(t-u)^{r}}{r!} du, \qquad 0 \le s, \ t \le 1$ 

An approximation to *f* is based only on some *noisy* information *y* about *f*. More specifically, the approximation is given as a function  $\varphi(y): [0, 1] \to \mathbb{R}$ , where *y* is of the form

$$y = N(f) + x,$$

with

$$N(f) = (f(t_1), f(t_2), ..., f(t_n))$$

and x having the zero mean n dimensional normal distribution with covariance matrix  $\sigma^2 I_n$ ,

$$x \sim \pi_{\sigma}^{n} = \mathcal{N}(0, \sigma^{2}I_{n}).$$

That is, the noise  $x_i = y_i - f(t_i)$  coming from different observations is independent and identically distributed,  $x_i \sim_{iid} \mathcal{N}(0, \sigma^2)$ . We assume that  $\sigma \ge 0$  allowing  $\sigma = 0$  to cover also the exact information case. The quality of approximation is given by its average  $L_p$ -error in the  $L_q$ -norm with respect to  $w^r$ , i.e.,

$$e_q^p(r,\sigma;\varphi,N) = \left(\int_{F^r} \int_{\mathbb{R}^n} \left( \|f - \varphi(N(f) + x)\|_q \right)^p \pi_\sigma^n(dx) w^r(df) \right)^{1/p}.$$

Here  $1 \leq p < \infty$  and  $1 \leq q \leq \infty$ . Letting  $\mathcal{N}_n$  be the set of all N consisting of at most n function evaluations, we are interested in the minimal error that can be attained using  $N \in \mathcal{N}_n$ ,

$$e_q^p(r,\sigma;n) = \inf_{N \in \mathcal{N}_n} \inf_{\varphi} e_q^p(r,\sigma;\varphi,N).$$

The minimal errors  $e_q^p(r, \sigma; n)$  have been obtained in the case of exact information where they are roughly equal to the average Kolmogorov *n*-widths. See, e.g., Speckman [13] and Ritter [11] for  $q < \infty$ , and Müller–Gronbach and Ritter [5], Ritter [10], and Wasilkowski [15] for  $q = \infty$ . Results on average *n*-widths can be found in Maiorov and Wasilkowski [4].

In the case of noisy information with p = q = 2 the errors  $e_2^2(r, \sigma; n)$  have been obtained by Plaskota [6] for r = 0 and Ritter [12] for  $r \ge 1$ . As noticed in Ritter [12], similar formulas can be derived for all p, q except for  $q = \infty$ . We now state those results precisely. We use notation  $a_n \simeq b_n$  to denote the same asymptotic behavior of sequences, i.e., this means that there are  $0 < m \le M < \infty$  such that  $m \le a_n/b_n \le M$  holds for sufficiently large n,  $n \ge n_0 = n_0(\sigma)$ . We stress that in all the asymptotic formulas for  $e_q^p(r, \sigma; n)$ with  $\sigma > 0$ , the constants m and M are independent of  $\sigma$ ; however,  $n_0(\sigma) \to \infty$  if  $\sigma \to 0$  or if  $\sigma \to \infty$ .

With this notation, for  $1 \leq q < \infty$  and  $\sigma \geq 0$  we have

$$e_q^p(r,\sigma;n) \simeq n^{-(r+1/2)} + \left(\frac{\sigma}{\sqrt{n}}\right)^{(2r+1)/(2r+2)},$$
 (1)

and for  $q = \infty$  and  $\sigma = 0$  we have

$$e_{\infty}^{p}(r, 0; n) \simeq n^{-(r+1/2)} \ln^{1/2} n.$$

The main purpose of this paper is to solve the missing case of the average case  $L_{\infty}$ -approximation with noise. Note that a similar problem, but for the worst case error over f, has been studied by Donoho [2] and Korostelev [3], who obtained the asymptotic constants for equidistant sampling. Results for the multivariate  $L_{\infty}$ -approximation in the same setting are given in Plaskota [9]. In the average case setting, we have the following theorem which is the main result of this paper.

MAIN THEOREM. For  $\sigma > 0$  we have

$$e_{\infty}^{p}(r,\sigma,n) \asymp \left(\frac{\sigma}{\sqrt{n}}\right)^{(2r+1)/(2r+2)} \ln^{1/2} n.$$

Thus, taking together the exact and noisy information cases, for  $\sigma \ge 0$  we obtain

$$e_{\infty}^{p}(r,\sigma;n) \simeq n^{-(r+1/2)} \ln^{1/2} n + \left(\frac{\sigma}{\sqrt{n}}\right)^{(2r+1)/(2r+2)} \ln^{1/2} n$$

In particular, comparing this with (1), we have  $e_{\infty}^{p}(r, \sigma; n) \simeq e_{q}^{p}(r, \sigma; n) \ln^{1/2} n$ , i.e., the minimal error of  $L_{\infty}$ -approximation is larger by a factor of  $\ln^{1/2} n$  than the minimal error of  $L_{q}$ -approximation with  $q < \infty$ , for both the exact and noisy information.

A proof of the Main Theorem is given in Section 2 and Section 3. In particular, we show that an order optimal  $L_{\infty}$ -approximation can be obtained by piecewise polynomial interpolation of degree r based on repetitive observations at equidistant points. In Section 4 we additionally note that the well-known smoothing spline approximation based on non-repetitive and equidistant observations also leads to an order optimal approximation.

The techniques used for proving the upper and lower bounds can be applied to obtain the already known formulas for  $L_q$ -approximation with  $1 \leq q < \infty$ , as indicated in a series of remarks.

#### 2. THE UPPER BOUND

We first need some facts from the case of exact information. Let  $N_n$  be information about function values at equidistant points,

$$N_n(f) = (f(1/n), f(2/n), ..., f(1)).$$

For exact data ( $\sigma = 0$ ) information  $N_n$  is order optimal. This is well known for  $L_q$ -approximation with  $q < \infty$ . A proof for  $q = \infty$  and r = 0 can be found in Ritter [10]. In what follows, we show optimality of  $N_n$  for  $q = \infty$ and  $r \ge 1$ . In this case, Maiorov and Wasilkowski [4] give us a lower bound  $n^{-(r+1/2)} \ln^{1/2} n$  for the minimal error; hence we only need to construct an approximation using  $N_n$  with error of that order.

Assume without loss of generality that *n* is a multiple of *r*, i.e., s = n/r is an integer. (Otherwise we take  $s = \lfloor n/r \rfloor$ .) For  $1 \le i \le s$  and  $0 \le j \le r$ , let

$$t_{i, j} = (i-1)/s + j/n.$$

Consider the approximation  $\varphi_n$  which uses information  $N_n$  and relies on piecewise polynomial interpolation of degree *r*. That is, for *t* in an interval  $[t_{i,0}, t_{i,r}]$ ,  $1 \le i \le s$ , we have

$$(\varphi_n(y_1, ..., y_n))(t) = (w_{i,r}(y_{(i-1)r}, y_{(i-1)r+1}, ..., y_{ir}))(t)$$

(with  $y_0 = 0$ ), where  $w_{i,r}(z_0, z_1, ..., z_r)$  is the polynomial of degree r taking  $z_i$  at the points  $t_{i,j}$ ,  $0 \le j \le r$ .

LEMMA 1. In the case of exact information and  $r \ge 1$  we have

$$e_{\infty}^{p}(r, 0; \varphi_{n}, N_{n}) = O(n^{-(r+1/2)} \ln^{1/2} n),$$

*i.e.*, the piecewise polynomial interpolation of degree r based on equidistant points is order optimal.

*Proof.* Let  $f \in F^r$ . Let  $f(z_1, z_2, ..., z_k)$  denote the divided difference of f of order k, i.e.,  $f(z_1)$  is the usual function value at  $z_1$ , and (for  $z_1 \neq z_k$ )

$$f(z_1, z_2, ..., z_k) = \frac{f(z_2, ..., z_k) - f(z_1, ..., z_{k-1})}{z_k - z_1}.$$

Using the well-known formula for the error of Lagrange interpolation we obtain that for any  $t \in [t_{i,0}, t_{i,r}]$ 

$$\begin{split} f(t) &- (\varphi_n(N_n(f)))(t) \\ &= f(t) - (w_{i,r}(f(t_{i,0}), ..., f(t_{i,r})))(t) \\ &= (t - t_{i,0}) \cdots (t - t_{i,r}) f(t_{i,0}, ..., t_{i,r}, t) \\ &= (t - t_{i,0}) \cdots (t - t_{i,r}) \frac{f(t_{i,1}, ..., t_{i,r}, t) - f(t_{i,0}, ..., t_{i,r-1}, t)}{t_{i,r} - t_{i,0}} \\ &= (t - t_{i,0}) \cdots (t - t_{i,r}) \frac{f^{(r)}(\xi_1(t))/r! - f^{(r)}(\xi_2(t))/r!}{1/s}, \end{split}$$

where  $\xi_k(t) \in [t_{i,0}, t_{i,r}], k = 1, 2$ . Hence

$$|f(t) - (\varphi_n(N_n(f)))(t)| \leq \frac{1}{s^r r!} \psi_i(f)$$

with

$$\psi_i(f) = \max\{|f^{(r)}(\xi_1) - f^{(r)}(\xi_2)| \colon t_{i,0} \leq \xi_1, \xi_2 \leq t_{i,r}\}.$$

For  $1 \leq i \leq s$ , define the functions

$$g_i(t) = \sqrt{s} \left( f^{(r)} \left( \frac{\lfloor ts \rfloor + t}{s} \right) - f^{(r)} \left( \frac{\lfloor ts \rfloor}{s} \right) \right), \qquad 0 \leqslant t \leqslant 1.$$

Then the  $g_i$ 's are independent and identically distributed according to the classical Wiener measure  $w^0$  on C([0, 1]). Moreover,

$$\psi_i(f) = s^{-1/2} \widetilde{\psi}(g_i)$$

with

$$\widetilde{\psi}(g) = \sup\{|g(\xi_1) - g(\xi_2)|: 0 \leq \xi_1, \xi_2 \leq 1\}.$$

We obtain that the error of  $\varphi_n$  using  $N_n$  can be bounded from above by

$$\begin{aligned} e_{\infty}^{p}(r,0;\varphi_{n},N_{n}) \\ &= \left(\int_{F^{r}} \|f-\varphi_{n}(N_{n}(f))\|_{\infty}^{p} w^{r}(df)\right)^{1/p} \\ &\leqslant (r!)^{-1} s^{-(r+1/2)} \left(\int_{F^{0}} \cdots \int_{F^{0}} (\max_{1\leqslant i\leqslant s} \widetilde{\psi}(g_{i}))^{p} w^{0}(dg_{1}) \cdots w^{0}(dg_{s})\right)^{1/p}. \end{aligned}$$

Since  $\operatorname{Prob}\{\widetilde{\psi}(g_i) > a\} \approx (2\pi)^{-1/2} \int_{|z| > a} e^{-z^2/2} dz$  as  $a \to \infty$ , see Billingsley [1], we have that the multiple integral above is asymptotically equal to the expected value of  $\max_{1 \le i \le s} |z_i|^p$  with  $z_i \sim_{iid} \mathcal{N}(0, 1)$ , which in turn behaves as  $\ln^{p/2} s$ . Hence

$$e_{\infty}^{p}(r, 0; \varphi_{n}, N_{n}) \leq (r!)^{-1} s^{-(r+1/2)} \ln^{1/2} s(1+o(1))$$
  
=  $\frac{r^{r+1/2}}{r!} n^{-(r+1/2)} \ln^{1/2} n(1+o(1)) \approx n^{-(r+1/2)} \ln^{1/2} n,$ 

as claimed.

Note that the approximation based on the piecewise polynomial interpolation is defined for  $r \ge 1$ . In the case of r = 0 the corresponding approximation would be

$$(\varphi_n(y))(t) = y_{\lfloor tn \rfloor/n}, \qquad 0 \leqslant t \leqslant 1.$$
(2)

Although  $\varphi_n(y)$  has discontinuities at j/n,  $\forall j$ , its error is well defined and

$$e_{\infty}^{p}(0, 0; \varphi_{n}, N_{n}) = \left(\int_{F^{0}} \|f - \varphi_{n}(N_{n}(f))\|_{\infty}^{p} w^{0}(df)\right)^{1/p}$$
  
=  $n^{-1/2} \left(\int_{F^{0}} \cdots \int_{F^{0}} (\max_{1 \le i \le n} \widetilde{\psi}(g_{i}))^{p} w^{0}(dg_{1}) \cdots w^{0}(dg_{n})\right)^{1/p}$   
 $\approx \sqrt{\frac{2 \ln n}{n}}.$ 

From Ritter [10] we know that the minimal error is in this case asymptotically equal to  $\sqrt{\ln n/(2n)}$ . (Actually the proof was given for p = 1 but the same holds for all  $p \ge 1$ .) Hence  $\varphi_n$  is only twice worse than the optimal approximation.

*Remark* 1. The same piecewise polynomial interpolation is order optimal also for all  $q < \infty$ . Indeed, in view of Hölder's inequality it suffices to consider  $p = q < \infty$ . Using the notation from the proof of Lemma 1 we obtain

$$\begin{split} e_q^q(r,0;\varphi_n,N_n) &= \left(\int_{F^r} \int_0^1 |f(t) - (\varphi_n(N_n(f)))(t)|^q \, dt \, w^r(df)\right)^{1/q} \\ &\leq \left(\int_0^1 \int_{F^r} |f(t) - (\varphi_n(N_n(f)))(t)|^q \, w^r(df) \, dt\right)^{1/q} \\ &\leq \frac{1}{r! \, s^r} \left(\sum_{i=1}^s \int_{t_{i,0}}^{t_{i,r}} \int_{F^r} (\psi_i(f))^q \, q^r(df) \, dt\right)^{1/q} \\ &= s^{-(r+1/2)} (r!)^{-1} \left(\int_{F^0} (\tilde{\psi}_i(g))^q \, w^0(dg)\right)^{1/q} \asymp n^{-(r+1/2)}. \end{split}$$

Obviously, the same holds for r = 0 and the piecewise constant approximation defined in (2).

We now use the approximation procedure  $\varphi_n$  to prove the upper bound of the Main Theorem. We assume that  $\sigma > 0$  and  $r \ge 0$ . Let  $N_m^k$  be information where observations at equidistant points are repeated k times,

$$N_m^k(f) = (\underbrace{f(1/n), ..., f(1/n)}_k, ..., \underbrace{f(1), ..., f(1)}_k)$$

For information

$$y = (y_{1,1}, ..., y_{1,k}, ..., y_{m,1}, ..., y_{m,k}) \in \mathbb{R}^{n_1},$$

where  $n_1 = mk$ , let  $\tilde{y} = (\tilde{y}_1, ..., \tilde{y}_m) \in \mathbb{R}^m$  be defined as

$$\tilde{y}_i = \frac{1}{k} \sum_{j=1}^k y_{i,j}, \qquad 1 \leq i \leq m.$$

Define the approximation  $\varphi_m^k$  as

$$\varphi_m^k(y) = \varphi_m(\tilde{y}),$$

where  $\varphi_m$  is as in Lemma 1 if  $r \ge 1$ , and  $\varphi_m$  is the linear spline interpolating data or the piecewise constant approximation defined in (2) if r = 0. Note that, due to linearity of  $\varphi_m$ , we equivalently have  $\varphi_m^k(y) = (1/k) \sum_{j=1}^k \varphi_m(y^j)$  with  $y^j = (y_{1,j}, ..., y_{m,j})$ .

In what follows, we write  $a_n(\sigma) = O(b_n(\sigma))$  iff there is a constant  $0 < M < \infty$  such that  $a_n(\sigma) \leq Mb_n(\sigma)$  holds for sufficiently large  $n, n \geq n_0$ . Here M is independent of  $\sigma$ , but  $n_0$  may depend on  $\sigma$ .

THEOREM 1. Let  $\sigma > 0$ . Let the number *m* of points and the number *k* of repetitions be chosen such that  $mk = n_1 \leq n$ ,

$$m \approx \left(\frac{\sigma}{\sqrt{n}}\right)^{-1/(r+1)}$$
 and  $k \approx n \left(\frac{\sigma}{\sqrt{n}}\right)^{1/(r+1)}$ 

Then for  $1 \leq p < \infty$  we have

$$e_{\infty}^{p}(r,\sigma;\varphi_{m}^{k},N_{m}^{k})=O\left(\left(\frac{\sigma}{\sqrt{n}}\right)^{(2r+1)/(2r+2)}\ln^{1/2}n\right)$$

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Proof. Letting 
$$\tilde{x} = \tilde{y} - N_m(f) \sim \mathcal{N}(0, \sigma^2/kI_m)$$
 we have  
 $e_{\infty}^p(r, \sigma; \varphi_m^k, N_m^k)$ 

$$= \left(\int_{F^r} \int_{\mathbb{R}^n} \|f - \varphi_m^k(N_m^k(f) + x)\|_{\infty}^p \pi_{\sigma}^{n_1}(dx) w^r(df)\right)^{1/p}$$

$$= \left(\int_{F^r} \int_{\mathbb{R}^m} \|f - \varphi_m(N_m(f) + \tilde{x})\|_{\infty}^p \pi_{\sigma/\sqrt{k}}^m(d\tilde{x}) w^r(df)\right)^{1/p}$$

$$\leqslant \left(\int_{F^r} \int_{\mathbb{R}^m} (\|f - \varphi_m(N_m(f))\|_{\infty} + \|\varphi_m(\tilde{x})\|_{\infty})^p \pi_{\sigma/\sqrt{k}}^m(d\tilde{x}) w^r(df)\right)^{1/p}$$

Observe that for all *m* and  $\tilde{x} \in \mathbb{R}^m$  we have  $\|\varphi_m(\tilde{x})\|_{\infty} \leq K \|\tilde{x}\|_{\infty}$ , where

$$K = \sup_{\|z\|_{\infty} \leq 1} \|\varphi_r(z)\|_{\infty} < \infty.$$

This and the inequality  $(|a| + |b|)^p \leq 2^{p-1}(|a|^p + |b|^p)$  yield

$$\begin{split} e_{\infty}^{p}(r,\sigma;\varphi_{m}^{k},N_{m}^{k}) \\ \leqslant 2^{1-1/p} \left( \int_{F^{r}} \int_{\mathbb{R}^{m}} \|f-\varphi_{m}(N_{m}(f))\|_{\infty}^{p} + \|\varphi_{m}(\tilde{x})\|_{\infty}^{p} \pi_{\sigma/\sqrt{k}}^{m}(d\tilde{x}) w^{r}(df) \right)^{1/p} \\ \leqslant 2^{1-1/p} \left( \int_{F^{r}} \|f-\varphi_{m}(N_{m}(f))\|_{\infty}^{p} w^{r}(df) + \left(\frac{K\sigma}{\sqrt{k}}\right)^{p} \int_{\mathbb{R}^{m}} \|z\|_{\infty}^{p} \pi_{1}^{m}(dz) \right)^{1/p}. \end{split}$$

Finally, we use Lemma 1 and the formulas for m and k to obtain

$$e_{\infty}^{p}(r,\sigma;\varphi_{m}^{k},N_{m}^{k}) = O((m^{-p(r+1/2)}\ln^{p/2}m + (\sigma/\sqrt{k})^{p}\ln^{p/2}m)^{1/p})$$
$$\approx \left(\frac{\sigma}{\sqrt{n}}\right)^{(2r+1)/(2r+2)}\ln^{1/2}n,$$

as claimed.

In the special case of r = 0, p = 1, and  $\varphi_m$  being the linear spline, the constant K = 1 and the error

$$e_{\infty}^{1}(O,\sigma;\varphi_{m}^{k},N_{m}^{k}) \leq \int_{F^{0}} \|f-\varphi_{m}(N_{m}(f))\|_{\infty} w^{0}(df) + \frac{\sigma}{\sqrt{k}} \int_{\mathbb{R}^{m}} \|z\|_{\infty} \pi_{1}^{m}(dz)$$
$$\approx \sqrt{\frac{\ln m}{2m}} + \frac{\sigma}{\sqrt{k}} \sqrt{2\ln m}$$

(as  $m \to \infty$ ). The optimal m and k are  $m \approx \sqrt{n}/(2\sigma)$  and  $k \approx 2\sigma \sqrt{n}$ , and then

$$e_{\infty}^{1}(0,\sigma;\varphi_{m}^{k},N_{m}^{k}) \leq \left(\frac{2\sigma \ln n}{\sqrt{n}}\right)^{1/2} (1+o(1)).$$
 (3)

*Remark* 2. We saw in the previous remark that for exact information the approximation  $\varphi_n$  is order optimal not only for  $q = \infty$  but also for  $1 \le q < \infty$ . Similarly, in the "noisy" case the approximation  $\varphi_m^k$  is order optimal for all finite q. Indeed, assume without loss of generality that p = q. Let

$$M = \left( \int_{\mathbb{R}^{r+1}} \|z\|_{\infty}^{q} \pi_{1}^{r+1}(dz) \right)^{1/q} < \infty.$$

Then

$$\begin{split} e_q^q(r,\sigma;\varphi_m^k,N_m^k) &\leq 2^{1-1/q} \left( \int_{F^r} \|f-\varphi_m(N_m(f))\|_q^q \, w^r(df) + \left(\frac{KM\sigma}{\sqrt{k}}\right)^q \right)^{1/q} \\ & \asymp \left(\frac{\sigma}{\sqrt{n}}\right)^{(2r+1)/(2r+2)}. \end{split}$$

In particular, for p = q = 2, r = 0, and  $\varphi_m$  the linear spline, we can calculate the exact error; namely,

$$\begin{split} e_{2}^{2}(0,\sigma;\varphi_{m}^{k},N_{m}^{k}) \\ &= \left(\int_{F^{0}}\|f-\varphi_{m}(N_{m}(f))\|_{2}^{2}w^{0}(df) + \frac{\sigma^{2}}{k}\int_{\mathbb{R}^{m}}\int_{0}^{1}|(\varphi_{m}(\tilde{x}))(t)|^{2} dt \,\pi_{1}^{m}(d\tilde{x})\right)^{1/2} \\ &= \left(\frac{1}{6m} + \frac{\sigma^{2}}{k} \left(\int_{0}^{1/m}\int_{\mathbb{R}}(ztm)^{2}\pi_{1}^{1}(dz) \,dt \right. \\ &+ (m-1)\int_{0}^{1/m}\int_{\mathbb{R}^{2}}(z_{2}tm - z_{1}(1-tm))^{2}\pi_{1}^{2}(dz) \,dt\right) \bigg)^{1/2} \\ &= \left(\frac{1}{6m} + \frac{2\sigma^{2}}{3k} \left(1 - \frac{1}{2m}\right)\right)^{1/2}. \end{split}$$

The optimal choice of *m* is  $m \approx \sqrt{n/(2\sigma)}$ . Then the number *k* of repetitions is roughly  $2\sigma \sqrt{n}$  and the error is asymptotically equal to

$$e_2^2(0,\sigma;\varphi_m^k,N_m^k) \approx \left(\frac{2\sigma}{3\sqrt{n}}\right)^{1/2}$$

This can be compared with the minimal error that can be obtained from non-repetitive *n* equidistant observations. In the latter case, this error asymptotically equals  $(\sigma/(2\sqrt{n}))^{1/2}$ , see Plaskota [6]; hence we lose about 15.6% using repetitions.

### 3. THE LOWER BOUND

We first show the following simple, but useful lemma.

LEMMA 2. Let  $\mu$  be a Gaussian measure on C([0, 1]) with covariance kernel R. Let  $\tilde{R}$  be the covariance kernel of the conditional (a posteriori) distribution of  $\mu$  with respect to independent noisy observations of  $f(t_1), ..., f(t_n)$  with variance  $\sigma^2$ . Then

$$\widetilde{R}(t,t) \ge \frac{\sigma^2 R(t,t)}{\sigma^2 + nR_{\max}}, \qquad 0 \le t \le 1,$$

where  $R_{\max} = \sup_{0 \le u \le 1} R(u, u)$ .

*Proof.* Suppose that a single observation at *u* is performed with variance

$$\sigma_u^2 = \sigma^2 R(u, u) / R_{\rm max}$$

instead of  $\sigma^2$ . (Or equivalently that only observations of the functionals af(t), where  $a^2 \leq R_{\max}/R(u, u)$ , with variance  $\sigma^2$  are allowed.) Let  $\tilde{R}_1$  be the corresponding conditional covariance kernel. The problem of maximally reducing  $\tilde{R}_1(t, t)$  is equivalent to approximating f(t) in the  $L_2$ -norm. It follows from Plaskota [7] (see also Plaskota [8, Sect. 3.8.1]) that the best way of doing this is to make all the *n* observations at *t*, and then

$$\widetilde{R}_{1}(t,t) = \frac{\sigma_{t}^{2} R(t,t)}{\sigma_{t}^{2} + nR(t,t)} = \frac{\sigma^{2} R(t,t)}{\sigma^{2} + nR_{\max}}.$$

The proof is complete with the observation that  $\sigma_t^2 \leq \sigma^2$  implies  $\tilde{R}(t, t) \geq \tilde{R}_1(t, t)$ .

Using this lemma we now prove the lower bound of Main Theorem. We write  $a_n(\sigma) = \Omega(b_n(\sigma))$  iff there is  $0 < m < \infty$  independent of  $\sigma$  such that  $a_n(\sigma) \ge mb_n(\sigma)$  for all sufficiently large  $n, n \ge n_0 = n_0(\sigma)$ .

Theorem 2. For  $\sigma > 0$  we have

$$e_{\infty}^{p}(r,\sigma;n) = \Omega\left(\left(\frac{\sigma}{\sqrt{n}}\right)^{(2r+1)/(2r+2)} \ln^{1/2} n\right).$$

*Proof.* Let  $m \ge 1$ . Let  $\tilde{w}^r$  be the conditional distribution on  $F^r$  given additional exact information that  $f^{(j)}(i/m) = 0$  for  $1 \le i \le m$  and  $0 \le j \le r$ . That is,  $\tilde{w}^r$  is the well-known *r*-fold Brownian bridge. Its mean element is zero and its covariance kernel R(s, t) is given as follows. Let  $\gamma_r = ((2r+1)(r!)^2)^{-1}$ . Then for  $(i-1)/m < s \le t < i/m$  we have

$$R(s, t) = R(t, s) = \gamma_r m^{-(2r+1)} (\tilde{s}(1+\tilde{t}))^{2r+1}$$

where  $\tilde{s} = sm - (i-1)$  and  $\tilde{t} = tm - (i-1)$ . On the other hand, if *s* and *t* are not in the same interval ((i-1)/m, i/m) then the variables f(s) and f(t) are independent and R(s, t) = 0.

Now, let  $u_i = (2i-1)/(2i)$ ,  $1 \le i \le m$ , and

$$||f||_{*} = \max_{1 \le i \le m} |f(u_{i})| \le ||f||_{\infty}.$$

It is clear that the minimal error for our original problem is bounded from below by the minimal error for a new problem with  $w^r$  replaced by  $\tilde{w}^r$  and with error measured in the seminorm  $\|\cdot\|_*$  instead of  $\|\cdot\|_\infty$ . That is, we now find

$$\tilde{e}_*^p(r,\sigma;n) = \inf_{\varphi,N} \left( \int_{F^r} \int_{\mathbb{R}^n} \max_{1 \le i \le m} |f(u_i) - \varphi_i(N(f) + x)|^p \, \pi_\sigma^n(dx) \, \tilde{w}^r(df) \right)^{1/p},$$

where  $N(f) = (f(t_1), ..., f(t_n))$  and  $\varphi_i(y) = (\varphi(y))(u_i)$ . To that end, observe that the random variables  $z_i = f(u_i)$  are independent (with respect to  $\tilde{w}^r$ ) and  $z_i \sim_{iid} \mathcal{N}(0, \lambda)$  with

$$\lambda = R(u_i, u_i) = \sup_{0 \le u \le 1} R(u, u) = \gamma_r(4m)^{-(2r+1)}.$$

Also, for  $t \in ((i-1)/m, i/m)$  and  $j \neq i$  the variables f(t) and  $z_j$  are independent. Thus a single observation at such a t can only reduce the variance of  $z_i$  and, in view of Lemma 2, the best way of doing this is to take  $t = u_i$ . Consequently we can restrict observations to those at the  $u_i$ 's and

$$\tilde{e}^{p}_{*}(r,\sigma;n) = \inf_{\varphi,N} \left( \int_{\mathbb{R}^{m}} \int_{\mathbb{R}^{n}} \max_{1 \le i \le m} |z_{i} - \varphi_{i}(N(z) + x)|^{p} \pi^{n}_{\sigma}(dx) \pi^{m}_{\lambda}(dz) \right)^{1/p},$$

where  $z = (z_1, ..., z_m)$ ,  $\varphi = (\varphi_1, ..., \varphi_m)$ , and information is of the form

$$N(z) = (z_{i_1}, ..., z_{i_n}), \qquad 1 \le i_i \le m$$

We obtained that the difficulty of the original problem is bounded from below by the difficulty of approximating a finite dimensional vector  $z \sim \mathcal{N}(0, \lambda I_m)$  from *n* noisy observations of its coordinates. The solution of the latter problem for p = 1 is given in Plaskota [9, see Lemma A2 of Appendix]; however, applying the same technique one can solve it for arbitrary  $p \ge 1$ . We have that the minimal error for the finite dimensional problem (and for *n* a multiple of *m*) is

$$\sigma \sqrt{\frac{m\lambda}{\sigma^2 m + \lambda n}} \left( \int_{\mathbb{R}^m} \|z\|_{\infty}^p \pi_1^m(dz) \right)^{1/p}.$$

Hence, taking into account the formula for  $\lambda$  and letting  $m \simeq (n/\sigma^2)^{1/(2r+2)}$ , we finally obtain

$$e_{\infty}^{p}(r,\sigma;n) \ge e_{\ast}^{p}(r,\sigma;n) \approx \sigma \sqrt{\frac{\gamma_{r}m}{\sigma^{2}m^{2r+2}+\gamma_{r}n}} \left( \int_{\mathbb{R}^{m}} \|m\|_{\infty}^{p} \pi_{1}^{m}(dz) \right)^{1/p}$$
$$\approx \sigma \sqrt{\frac{2\gamma_{r}m\ln m}{\sigma^{2}m^{2r+2}+\gamma_{r}n}} \asymp \left(\frac{\sigma}{\sqrt{n}}\right)^{(2r+1)/(2r+2)} \ln^{1/2} n,$$

as claimed.

Observe that in the case of r = 0 and p = 1 we have  $\lambda = 1/(4m)$ . Hence, taking  $m \approx \sqrt{n}/(2\sigma)$ , we obtain

$$e_{\infty}^{1}(0,\sigma;n) \ge \sigma \sqrt{\frac{2m\ln m}{4\sigma^{2}m^{2}+n}} \left(1+o(1)\right) \approx \left(\frac{\sigma\ln n}{4\sqrt{n}}\right)^{1/2}$$

Comparing this with (3) we can write

$$e_{\infty}^{1}(0,\sigma;n) \approx a_{n} \left(\frac{\sigma \ln n}{\sqrt{n}}\right)^{1/2}$$

where  $1/2 \leq a_n \leq \sqrt{2}$ .

*Remark* 3. The proof of Theorem 2 can also be easily adopted to obtain lower bounds on the minimal errors for  $1 \le q < \infty$ . Indeed, let without loss of generality p = q. Let  $\tilde{R}_r$  be the conditional covariance kernel after *n* noisy observations  $N(f) = (f(t_1), ..., f(t_n))$ , and let  $\lambda_t = \tilde{R}_r(t, t)$ . Let  $E_\eta(\psi(x))$ denote the expected value of  $\psi(x)$  with respect to  $x \sim \mathcal{N}(0, \eta)$ . Proceeding as in, e.g., Ritter [10], we can write that the minimal error for the information N equals

$$\inf_{\varphi} e_q^q(r,\sigma;\varphi,N) = \left(\int_0^1 E_{\lambda_t}(|x|^q) \, dt\right)^{1/q} = \left(E_1(|x|^q)\right)^{1/q} \left(\int_0^1 \lambda_t^{q/2} \, dt\right)^{1/q}.$$

Using Lemma 2 and notation from the proof of Theorem 2 we find that

$$\lambda_{t} \geq \frac{\sigma^{2} \gamma_{r}}{\sigma^{2} m^{2r+1} + 4^{-(2r+1)} k_{i} \gamma_{r}} (\tilde{t}(1-\tilde{t}))^{2r+1},$$

where  $m \ge 1$  and  $k_i$  is the number of points  $t_i$  in the interval ((i-1)/m, i/m). Hence

$$\begin{split} \inf_{\varphi} e_{q}^{q}(r,\sigma;\varphi,N) &\geq (E_{1}(|x|^{q}))^{1/q} \left(\sum_{i=1}^{m} \left(\frac{\sigma^{2}\gamma_{r}}{\sigma^{2}m^{2r+1}+4^{(-(2r+1))}k_{i}\gamma_{r}}\right)^{q/2} \\ &\times \int_{0}^{1} \left(\tilde{t}(1-\tilde{t}))^{q(r+1/2)} dt\right)^{1/q} \\ &= \left(E_{1}(|x|^{q}) \int_{0}^{1} u((1-u))^{q(r+1/2)} du\right)^{1/q} \\ &\times \left(\frac{1}{m} \sum_{i=1}^{m} \left(\frac{\sigma^{2}\gamma_{r}}{\sigma^{2}m^{2r+1}+4^{-(2r+1)}k_{i}\gamma_{r}}\right)^{q/2}\right)^{1/q}. \end{split}$$

The last expression is minimized by  $k_i = n/m$ ,  $\forall i$ . Thus taking  $m \simeq (n/\sigma^2)^{1/(2r+2)}$  we finally obtain

$$\begin{split} \inf_{\varphi} e_{q}^{q}(r,\sigma;\varphi,N) &= \Omega\left(\left(\frac{1}{m}\sum_{i=1}^{m} \left(\frac{\sigma^{2}\gamma_{r}}{\sigma^{2}m^{2r+2} + 4^{-(2r+1)}(n/m)\gamma_{r}}\right)^{q/2}\right)^{1/q}\right) \\ &\asymp \left(\frac{\sigma^{2}m}{\sigma^{2}m^{2r+2} + n}\right)^{1/2} \asymp \left(\frac{\sigma}{\sqrt{n}}\right)^{(2r+1)/(2r+2)}, \end{split}$$

as claimed. See also Plaskota [6] for a similar proof in the special case of r = 0 and p = q = 2.

# 4. NON-REPETITIVE OBSERVATIONS AND SMOOTHING SPLINES

In Section 2 we constructed an order optimal approximation based on repetitive observations. In practice one often uses *non*-repetitive observations at equidistant points, i.e.,  $N_n(f) = (f(1/n), f(2/n), ..., f(1))$ . It can be easily seen that if  $\sigma > 0$  then the usual piecewise polynomial approximation does not do the job in this case and we are forced to make some smoothing. That is, as an approximation to f one uses the smoothing spline  $\varphi(y) = \varphi_{spl}(y)$  which is given as the minimizer of

$$\sigma^2 \cdot \int_0^1 (f^{(r+1)}(u))^2 \, du + \sum_{j=1}^n (y_j - f(j/n))^2$$

over  $f \in W_2^{r+1}(0, 1)$ ,  $f^{(i)}(0) = 0$ ,  $0 \le i \le r$ . It is known that the smoothing spline approximation is best possible in the sense that it minimizes the error  $e_q^p(r, \sigma; \varphi, N_n)$  over all  $\varphi$  using  $N_n$ , see, e.g., Plaskota [8, Sect. 3.6].

It is also known that information  $N_n$  together with  $\varphi_{spl}$  provides an order optimal approximation for  $q < \infty$ , see Ritter [11, 12]. A natural question is whether this is also the case for  $q = \infty$ .

Theorem 3. For  $\sigma > 0$  we have

$$e_{\infty}^{p}(r,\sigma;\varphi_{\rm spl},N_{n}) = O\left(\left(\frac{\sigma}{\sqrt{n}}\right)^{(2r+1)/(2r+2)} \ln^{1/2}n\right),$$

i.e., the smoothing splice approximation  $\varphi_{spl}$  based on the equidistant and non-repetitive observations  $N_n$  is order optimal for uniform approximation.

*Proof.* We only sketch the proof since it makes use of the ideas already applied for proving the upper bound of Section 2.

Since the approximation  $\varphi_{spl}$  is best possible when using  $N_n$ , it suffices to show the order optimality of another approximation that uses  $N_n$ . This approximation is defined as follows.

Let *m* and *k* be chosen as in Theorem 1. We can assume without loss of generality that mk = n and *m* is a multiple of *r*. Then  $N_n = (N_{n,0}, N_{n,1}, ..., N_{n,k-1})$  with

$$N_{n, j} = (f(1/m - j/n), f(2/m - j/n), ..., f(1 - j/n)), \qquad 0 \leqslant j \leqslant k - 1.$$

Let  $\varphi_{n, j}$  be an approximation that uses information  $N_{n, j}$  and is order optimal for exact information; e.g., one can take (with some obvious modifications) the piecewise polynomial approximation of Lemma 1. Then we let

$$\tilde{\varphi}_n(y) = \frac{1}{k} \sum_{j=0}^{k-1} \varphi_{n,j}(y^j),$$

where  $y = (y^0, ..., y^{k-1}) \in \mathbb{R}^n$  and  $y^j \in \mathbb{R}^m$ ,  $\forall j$ . Note that  $\tilde{\varphi}_n$  can be viewed as another smoothing procedure that uses the non-repetitive and equidistant observations.

Repeating the corresponding part of the proof of Theorem 1, we find that

$$\begin{split} e_{\infty}^{p}(r,\sigma;\tilde{\varphi}_{n},N_{n}) \\ \leqslant 2^{1-1/p} \left( \int_{F^{r}} \left\| \frac{1}{k} \sum_{j=0}^{k-1} \left( f - \varphi_{n,j}(N_{n,j}(f)) \right) \right\|_{\infty}^{p} w^{r}(df) \\ &+ \sigma^{p} \int_{\mathbb{R}^{m}} \cdots \int_{\mathbb{R}^{m}} \left\| \frac{1}{k} \sum_{j=0}^{k-1} \varphi_{n,j}(x^{j}) \right\|_{\infty}^{p} \pi_{1}^{m}(dx^{0}) \cdots \pi_{1}^{m}(dx^{k-1}) \right)^{1/p}. \end{split}$$

Since all the  $\varphi_{n,j}$ 's are order optimal for *m* observations, the first integral above behaves as  $m^{-p(r+1/2)} \ln^{p/2} m$ . The second (multiple) integral in turn

behaves as  $k^{-p/2} \ln^{p/2} m$ , due to independency of  $\varphi_{n,j}(x^j)$  for  $0 \le j \le k-1$ . Hence, using the formulas for *m* and *k* we obtain

$$e_{\infty}^{p}(r,\sigma;\tilde{\varphi}_{n},N_{n})=O\left(\left(\frac{\sigma}{\sqrt{n}}\right)^{(2r+1)/(2r+2)}\ln^{1/2}n\right),$$

as claimed.

Obviously, a similar idea can be used to prove the order optimality of  $N_n$  in the case of  $q < \infty$ .

Note. Lemma 1 is a result of e-mail conversations with Klaus Ritter.

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